#### Interacting Ensemble MCMC and Fast Entropically Regularized SDP

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[ML, Jonathan Weare, and Anna Zhang,](#page-3-0) Ensemble Markov chain Monte Carlo with [teleporting](#page-3-0) walkers, SIAM/ASA JUQ [10, 860 \(2022\) \[arXiv:2106.02686\]](#page-3-0)

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#### **[Fast Entropically Regularized SDP](#page-25-0)**

# Sampling

Given the ability to evaluate  $U(x)$ , for  $x \in \mathcal{X}$ , we want to draw independent samples from

$$
\pi(x) = \frac{1}{Z}e^{-U(x)},
$$

where  $Z$  is a suitable (unknown) normalizing constant

- Ubiquitous applications in scientific computing:
	- Bayesian inference (sampling from posterior distribution)
		- Data science, computational astronomy, inverse problems, etc.
		- Often low-to-moderate dimensional but too high-dimensional for quadrature
	- Computational chemistry (sampling molecular configurations)
	- Quantum Monte Carlo (many methods)
	- Optimization (simulated annealing, etc.)
	- ...and many more!

## Markov chain Monte Carlo

- Most widely-used approach is Markov chain Monte Carlo (MCMC)
- Idea: construct a Markov chain  $g(y|x)$  whose invariant/equilibrium measure is  $\pi$
- Major generic frameworks for MCMC (can be combined!)-
	- Metropolis-Hastings: let q be any Markov chain, propose move  $x \rightarrow x'$ according to  $q$  and accept with probability

$$
A = \min\left(1, \frac{\pi(x')}{\pi(x)} \frac{q(x|x')}{q(x'|x)}\right)
$$

- Integrator-based methods: chain defined by discrete-time integration of an SDE
	- For example overdamped Langevin dynamics are defined by

$$
dX_t = -\nabla U(X_t) dt + \sqrt{2} dB_t,
$$

and can be Metropolis-adjusted (MALA)

See also underdamped Langevin and Hamiltonian Monte Carlo (HMC)

# **Metastability**

- All of these generic approaches can suffer from metastability
- In this case, the autocorrelation time (i.e., number of steps required to get an effectively independent sample) can be arbitrarily long



Figure: Illustration of metastability for Langevin dynamics. Colors indicate values of  $\it U.$  (Recall  $\pi \propto e^{-U}$ .)

### Interacting ensemble MCMC

**Idea:** instead of sampling  $x \sim \pi(x)$  directly, we consider an ensemble

$$
\mathsf{x}=(x_1,\ldots,x_N)\in\mathcal{X}^N
$$

of N walkers and sample

$$
x \sim \Pi(x) = \prod_{i=1}^N \pi(x_i)
$$

- Then each walker individually samples from  $\pi$ , as originally desired
- Although the walkers are distributed independently, our proposal will allow interaction between them
	- We will Metropolize our interacting-walker proposal to preserve the joint distribution Π
- Assume we are given any proposal  $q(y|x)$
- $\bullet$  Uniformly select walker index  $j \in \{1, \ldots, N\}$ 
	- The j-th walker will be cloned and then moved according to  $q$
	- Specifically, sample  $z \sim q(\cdot | x_i)$

# Teleporting proposal



Figure: Illustration of teleporting proposal. Think of the target density  $\pi$  as uniform for simplicity.

# Teleporting proposal

- Then we will sample an index *i* (possibly  $i = j$ ) for deletion
- i.e., we will propose  $x_i \leftarrow z$ 
	- If  $i \neq j$ , it's as if we have proposed teleporting walker i to be near walker j
- Specifically, *i* is sampled according to the importance weights

$$
w_i \propto \frac{q(x_i \mid z) + \sum_{k \neq i}^N q(x_i \mid x_k)}{\pi(x_i)},
$$

where the weights are normalized to sum to one

- Choice guarantees acceptance probability of 1 in the infinite-walker limit  $N \rightarrow \infty$
- We do not delete any walker that is 'lonely,' unless we have just cloned that walker

# Teleporting proposal



Figure: Illustration of teleporting proposal. Think of the target density  $\pi$  as uniform for simplicity.

- **•** Can try to get theoretical understanding via mean-field limit
- $\bullet$  In the limit of large N we can approximate the empirical measure of the walker positions

$$
\mu:=\frac{1}{N}\sum_{i=1}^N \delta_{x_i}
$$

by a continuous density function, i.e.,

 $d\mu(x) \approx \rho(x) dx$ 

#### Mean-field limit

Obtain mean-field evolution for the density

$$
\partial_t \rho(x) = \left[1 - \frac{1}{Z_\rho} \frac{\rho(x)}{\pi(x)}\right] Q_\rho(x)
$$

 $\bullet$   $Z_{\rho}$  is the constant that guarantees conservation of total probability

$$
\int \partial_t \rho \, dx = 0
$$

 $\bullet$  Q is the Markov transition kernel operator

$$
\mathcal{Q}\rho(x) = \int q(x \,|\, y) \,\rho(y) \,dy
$$

# Mean-field limit

**•** The mean-field dynamics enjoy convergence to  $\pi$  that is monotone in the Pearson  $\chi^2$ -divergence

$$
\chi^2(\pi \, \| \, \rho) = \int \left(1 - \frac{\pi}{\rho}\right)^2 \, \rho \, dx
$$

Aside: dynamics also admit interpretation as a gradient flow for the *reversed*  $\chi^2$ -divergence

#### Theorem (ML, Weare, Zhang)

Under suitable technical conditions,  $\chi^2(\pi \, \|\, \rho_t)$  is monotone decreasing. Moreover, there exists C independent of t such that

$$
\chi^2(\pi \,\|\,\rho_t) \leq C e^{-t/\gamma_\infty},
$$

where  $\gamma_{\infty} := \frac{1}{2} ||\pi/\mathcal{Q}\pi||_{\infty}$ .

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where  $\gamma_{\infty} := \frac{1}{2} ||\pi / \mathcal{Q}\pi||_{\infty}$ .

- Asymptotic rate of convergence for the non-interacting ensemble is controlled by the spectral gap of  $Q$
- Asymptotic rate of convergence for our scheme is **not** limited by the spectral gap
	- For a narrow proposal, rate  $\approx$  2 independent of proposal

**• Consider the double-well potential** 

$$
U(x) = \beta(x^4 - x^2),
$$

where  $\beta$  is an inverse temperature parameter controlling the depth of the two wells

Use Gaussian proposal  $q(y \,|\, x) \propto e^{-\frac{1}{2\sigma^2}(y-x)^2}$ 



Figure: Graph of  $\pi(x)$  for  $\beta = 5$ .



Figure:  $\rho_t$  according to the mean-field dynamics with  $\beta = 5$ ,  $\sigma = 0.0125$  at times  $t = 0, 2.5, 5, 7.5, 10, 12.5, 15, 17.5, 20, 22.5, ordered left-to-right, then$ bottom-to-top.



Figure:  $\rho_t$  according to the mean-field dynamics for a non-interacting ensemble with  $\beta = 5$ ,  $\sigma = 0.0125$  at several different times. Note that even by time  $t = 1000$ , the dynamics are far from convergence.



Figure: Convergence of  $\mathbb{P}_{X\sim\rho}(X\geq 0)$  for interacting dynamics (left) and non-interacting dynamics (right), for several different values of  $\beta$ ,  $\sigma$ . Note the different horizontal and vertical axis scales at left and right.

### Bayesian hyperparameter estimation

- We consider a multimodal Bayesian posterior sampling problem introduced in [Yao, Vehtari, and Gelman (2020)]
- Goal is to estimate hyperparameters in Gaussian process regression
- Observe data  $\left(x_i, y_i\right)$  and assume that

$$
y_i = f(x_i) + \varepsilon_i,
$$

where  $f\sim \mathcal{GP}(0,\Sigma)$ ,  $\varepsilon_i\sim \mathcal{N}(0,\sigma^2)$  i.i.d. noise, and

$$
\Sigma(x_1,x_2)=\alpha^2\left(-\frac{(x_1-x_2)^2}{\rho^2}\right)
$$

• Place indepedent Cauchy priors on our hyperparameters  $\theta = (\alpha, \rho, \sigma)$ • Sample from posterior distribution  $p(\theta | y)$ 

### Bayesian hyperparameter estimation



Figure: Posterior  $(\alpha, \rho)$  marginal (left) and  $\rho$  marginal (right).

### Bayesian hyperparameter estimation



Table: Integrated autocorrelation time. We see an over 20-fold efficiency gain by considering an interacting scheme with  $N = 50$  instead of a single walker, assuming cost is dominated by the the number of density evaluations (usually the bottleneck).

# Results not shown

- Similar results for the case of multivariate Gaussian process, where the data  $x_i \in \mathbb{R}^3$  (9-dimensional hyperparamter)
	- 16-fold efficiency gain of  $N = 100$  over  $N = 1$
- Paper also considers extension for interaction of a subset of variables
- Ongoing work:
	- Push the advantage to larger ensemble scales ( $N\sim 10^5$ -10 $^6)$  with a modified scheme allowing fast kernel operations for walker interaction and parallel density evaluations
	- Nonlocal proposals can still provide huge computational speedup even for unimodal densities!



Figure: IAT as a function of ensemble size for GPR hyperparameter posterior sampling.

- Related work arises by starting with a Fokker-Planck equation for a birth-death stochastic process, then considering a discrete-time particle approximation
	- Y. Lu, J. Lu, and J. Nolen [arXiv:1905.09863]
	- G. Rostkoff, S. Jelassi, J. Bruna, and E. Vanden-Eijnden [arXiv:1902.01843]
	- M. Gabrie, G. Rostkoff, and E. Vanden-Eijnden [arXiv:2105.12603]

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#### <sup>2</sup> [Fast Entropically Regularized SDP](#page-25-0)

- Semidefinite programs arise in many settings, often from the relaxation of an underlying difficult problem
- The most fundamental examples are from 0-1 combinatorial optimization, starting from [Goemans and Williamson (1995)]
	- See also the Lassere Hierarchy, starting with [Lasserre (2001)], as well as [Wainright and Jordan (2008)], for systematic approaches
- My interest in SDP comes from *marginal relaxations* for scientific computing problems:
	- Density functional theory [Khoo, Lin, ML, and Ying (2020)]
	- Continuous global optimization [Chen, Khoo, and ML (2020)]
	- . Quantum many-body problems [Lin and ML (2022)], [Khoo and ML (2022)]

# Max-Cut problem

• Given a graph  $(V, E)$ , want to color the vertices white/black so that as many edges as possible connect unlike colors



Figure: Maximum cut of a small graph

• Formally, if the vertices are indexed by  $i = 1, \ldots, n$ , want to solve:

$$
\min_{\{-1,1\}^n} \sum_{i,j\,:\,(i,j)\in E} x_i x_j
$$

#### NP-complete!

Hard to do much better than enumerating all 2<sup>n</sup> possibilities for  $x = (x_i)$ 

### Goemans-Williamson relaxation

On the domain  $x \in \{-1,1\}^N$ , rewrite the objective:

$$
\sum_{i,j \,:\, (i,j) \in E} x_i x_j = \sum_{i,j=1}^N A_{ij} x_i x_j = x^\top A x = \mathsf{Tr}[A x x^\top],
$$

where A is the adjacency matrix of the graph

Let

$$
X = xx^\top
$$

and observe that  $diag(X) = 1, X \succeq 0$ 

If we optimize  $X \in \mathbb{R}^{n \times n}$  subject only to these constraints, we obtain a relaxation of the original problem, providing a lower bound on the optimal value

# Goemans-Williamson relaxation

• Specifically

minimize Tr[AX]  $X \in \mathbb{R}^{n \times n}$ subject to  $X \succeq 0$ ,  $diag(X) = 1$ 

- This relaxation is due to Goemans and Williamson (1995)
	- They also provide a randomized rounding procedure from the solution  $X$ to an element  $x \in \{-1,1\}^n$
	- Plugging in x yields an upper bound guaranteed to yield an upper bound achieving an approximation ratio of

#### $\alpha \approx 0.878$

- In fact it is conjectured [Khot et al (2007)] to be the best possible guaranteed approximation ratio, and it is known [Trevisan et al (2000)] that  $> 0.941$  is NP-hard
- Aside from interest in Max-Cut per se, the GW relaxation is the prototypical semidefinite relaxation and SDP

A general SDP can be written

minimize 
$$
\text{Tr}[CX]
$$
  
\nsubject to  $X \succeq 0$ ,  
\n $\text{Tr}[A_k X] = b_k, \quad k = 1, ..., m$ ,

though sometimes alternative equivalent presentations may be preferred based on structure

# Review of optimization approaches

- How to solve an SDP? There are several categories of methods:
	- Interior point methods: strong convergence guarantees but very poor scaling per iteration
	- Augmented Lagrangian / ADMM-type methods: weaker convergence guarantees but optimal-in-general  $O(n^3)$  scaling per iteration (e.g., SDPNAL, cf. Toh et al)
	- Low-rank methods: exploit low-rank assumption on solution, e.g., SDPLR [Burer and Monteiro (2003)] and SketchyCGAL [Yurtsever et al (2021)]
	- TCS-style algorithms: e.g., MMWU [Arora and Kale (2007)]
- We want linear scaling (assuming sparsity of the cost and constraint matrices) without a low-rank assumption
	- The MMWU has nice theoretical scaling guarantees but impractical to implement!
- **This work:** first practical linear-scaling algorithm achieving a fixed approximation ratio for Max-Cut (though applies more broadly)
- Inspired by the success of the **entropic regularization of optimal** transport [Cuturi 2013], which is a *linear program*, we are motivated to consider the entropic regularization of  $SDP$  as a general computational tool
	- In addition to quantum statistical mechanics literature, see [Krechetov (2019)], [Lin and ML (2022)], and [Pavlov et al (2022)] for other uses
- $\bullet$  For a positive definite matrix X define the von Neumann entropy

$$
S(X) = \mathsf{Tr}[X \log X] - \mathsf{Tr}[X]
$$

Can be viewed as a quantum analog of Shannon's classical entropy, fundamental in quantum information theory, cf. [Nielsen and Chuang]

- Von Neumann entropy noncommutative/quantum analog of classical entropy, appearing in quantum information theory
- Consider the regularized problem, where  $\beta \in 0, \infty$ ) is a regularization parameter ('inverse temperature'):

$$
\begin{array}{ll}\text{minimize} & \mathsf{Tr}[CX] + \beta^{-1}S(X) \\ \text{subject to} & \mathsf{Tr}[A_k X] = b_k, \ \ k = 1, \dots, m \end{array}
$$

• Note that the entropy acts as a **barrier** to the boundary of  $\{X \succeq 0\}$  and also makes the problem strictly convex

### Dual problem

- Restrict to case of diagonal constraint  $diag(X) = b$  for simplicity
- The dual problem is unconstrained:

$$
\max_{\lambda \in \mathbb{R}^n} \quad b \cdot \lambda - \beta^{-1} \text{Tr} \left[ e^{-\beta (C - \text{diag}(\lambda))} \right]
$$

• In quantum statistical mechanics interpretation:

- $C_{\lambda} := C \text{diag}(\lambda)$  is an effective **Hamiltonian**
- $\bullet$   $\beta$  is the inverse temperature
- $\mathsf{Z}_{\beta,\lambda}:=\mathsf{Tr}[e^{-\beta\mathsf{C}_\lambda}]$  is the **partition function**
- $\mathcal{X}_{\beta,\lambda}:=e^{-\beta\mathcal{C}_\lambda}$  is the (unnormalized) **density operator**
- $\mathcal{F}_{\beta,\lambda}:=-\beta^{-1}Z_{\beta,\lambda}$  is (kind of) the free energy
- The gradient of the dual objective

$$
b-\mathrm{diag}(X_{\beta,\lambda})
$$

Hence we want to find a **dual solution**  $\lambda^*$  such that  $diag(X_{\beta,\lambda^*}) = b$ , and this  $X_{\beta,\lambda^*}$  is in fact the **primal solution** of the regularized problem

### Stochastic diagonal estimation

- How to compute  $\mathrm{diag}(\mathsf{X}_{\beta,\lambda})=\mathrm{diag}(\mathsf{e}^{-\beta \mathsf{C}_\lambda})$  ?
	- Forming the matrix exponential, even if  $\mathsf{C}_\lambda$  is sparse, consumes  $\mathcal{O}(n^3)$ cost
- Randomized approach which has appeared in the GPR literature [Mathur et al (2021)]:

$$
\mathrm{diag}(X)=\mathbb{E}_{z\sim\mathcal{N}}\left[(X^{1/2}z)\odot(X^{1/2}z)\right],
$$

where z is a standard Gaussian random vector

- We prove **concentration bounds** for the corresponding estimator
	- Relative error of estimator is essentially problem-independent
- Hence we only need to compute matrix-vector multiplications

$$
X_{\beta,\lambda}^{1/2}z = e^{-\frac{\beta}{2}C_{\lambda}}z
$$

Fast matrix-free algorithm available [Al-Mohy and Higham (2011)], or alternatively matrix-free Chebyshev expansion [Driscoll, Hale, and Trefethen (2014)]

- In fact for Max-Cut we do not apply dual gradient ascent, but introduce a specialized noncommutative matrix scaling approach
	- **But still makes use of the same estimator**
- Not discussed: 'fermionic' entropic regularization allows us to solve other problems, such as the **spectral embedding** of a graph with  $n$ vertices into  $\mathbb{R}^k$ 
	- Improve  $O(nk^2)$  of standard eigensolver approach to  $O(nk)$  randomized approximate algorithm

#### Max-Cut results: convergence profile



Figure: Convergence profile for various system sizes n and regularization parameters β (solid lines for  $β = 10$ , dotted lines for  $β = 32$ , dashed lines for  $β = 100$ )

#### Max-Cut results: approximation ratio



Figure: Approximation ratio obtained as a function of system size, for various regularization parameters  $\beta$ 

#### MCMC:

ML, J. Weare, and A. Zhang, Ensemble Markov chain Monte Carlo with teleporting walkers, submitted (anticipated SIAM/ASA Journal on Uncertainty Quantification)

#### SDP:

ML, Fast randomized entropically regularized semidefinite programming, preprint [arXiv:2303.12133]

#### Thank you very much for your attention!