Interacting Ensemble MCMC and Fast Entropically Regularized SDP

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Interacting Ensemble MCMC

• ML, Jonathan Weare, and Anna Zhang, Ensemble Markov chain Monte Carlo with teleporting walkers, SIAM/ASA JUQ 10, 860 (2022) [arXiv:2106.02686]

2 Fast Entropically Regularized SDP

• ML, Fast randomized entropically regularized semidefinite programming, preprint [arXiv:2303.12133].



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Sampling

• Given the ability to evaluate U(x), for $x \in \mathcal{X}$, we want to draw **independent samples** from

$$\pi(x)=\frac{1}{Z}e^{-U(x)},$$

where Z is a suitable (unknown) normalizing constant

- Ubiquitous applications in scientific computing:
 - Bayesian inference (sampling from posterior distribution)
 - Data science, computational astronomy, inverse problems, etc.
 - Often low-to-moderate dimensional but too high-dimensional for quadrature
 - Computational chemistry (sampling molecular configurations)
 - Quantum Monte Carlo (many methods)
 - Optimization (simulated annealing, etc.)
 - ...and many more!

Markov chain Monte Carlo

- Most widely-used approach is Markov chain Monte Carlo (MCMC)
- Idea: construct a Markov chain g(y | x) whose invariant/equilibrium measure is π
- Major generic frameworks for MCMC (can be combined!)—
 - Metropolis-Hastings: let q be any Markov chain, propose move $x \to x'$ according to q and accept with probability

$$A = \min\left(1, \frac{\pi(x')}{\pi(x)} \frac{q(x \mid x')}{q(x' \mid x)}\right)$$

- Integrator-based methods: chain defined by discrete-time integration of an SDE
 - For example overdamped Langevin dynamics are defined by

$$dX_t = -\nabla U(X_t) \, dt + \sqrt{2} \, dB_t,$$

and can be Metropolis-adjusted (MALA)

• See also underdamped Langevin and Hamiltonian Monte Carlo (HMC)

Metastability

- All of these generic approaches can suffer from metastability
- In this case, the autocorrelation time (i.e., number of steps required to get an effectively independent sample) can be arbitrarily long



Figure: Illustration of metastability for Langevin dynamics. Colors indicate values of U. (Recall $\pi \propto e^{-U}$.)

Interacting ensemble MCMC

• Idea: instead of sampling $x \sim \pi(x)$ directly, we consider an ensemble

$$\mathbf{x} = (x_1, \ldots, x_N) \in \mathcal{X}^N$$

of N walkers and sample

$$\mathbf{x} \sim \Pi(\mathbf{x}) = \prod_{i=1}^N \pi(x_i)$$

- Then each walker individually samples from π , as originally desired
- Although the walkers are distributed independently, our **proposal** will allow interaction between them
 - $\bullet\,$ We will Metropolize our interacting-walker proposal to preserve the joint distribution $\Pi\,$

- Assume we are given any proposal q(y | x)
- Uniformly select walker index $j \in \{1, \dots, N\}$
 - The j-th walker will be cloned and then moved according to q
 - Specifically, sample $z \sim q(\cdot \,|\, x_j)$

Teleporting proposal



Figure: Illustration of teleporting proposal. Think of the target density π as uniform for simplicity.

Teleporting proposal

- Then we will sample an index i (possibly i = j) for deletion
- i.e., we will propose $x_i \leftarrow z$
 - If $i \neq j$, it's as if we have proposed teleporting walker i to be near walker j
- Specifically, *i* is sampled according to the importance weights

$$w_i \propto rac{q(x_i \mid z) + \sum_{k
eq i}^N q(x_i \mid x_k)}{\pi(x_i)},$$

where the weights are normalized to sum to one

- Choice guarantees acceptance probability of 1 in the infinite-walker limit $N \to \infty$
- We do not delete any walker that is 'lonely,' unless we have just cloned that walker

Teleporting proposal



Figure: Illustration of teleporting proposal. Think of the target density π as uniform for simplicity.

- Can try to get theoretical understanding via mean-field limit
- In the limit of large N we can approximate the empirical measure of the walker positions

$$\mu := \frac{1}{N} \sum_{i=1}^{N} \delta_{x_i}$$

by a continuous density function, i.e.,

 $d\mu(x) \approx \rho(x) \, dx$

Mean-field limit

• Obtain mean-field evolution for the density

$$\partial_t \rho(x) = \left[1 - \frac{1}{Z_{\rho}} \frac{\rho(x)}{\pi(x)}\right] \mathcal{Q}\rho(x)$$

• $Z_{
ho}$ is the constant that guarantees conservation of total probability

$$\int \partial_t \rho \, dx = 0$$

• \mathcal{Q} is the Markov transition kernel operator

$$\mathcal{Q}\rho(x) = \int q(x \mid y) \, \rho(y) \, dy$$

Mean-field limit

• The mean-field dynamics enjoy convergence to π that is monotone in the Pearson $\chi^2\text{-divergence}$

$$\chi^2(\pi \parallel \rho) = \int \left(1 - \frac{\pi}{\rho}\right)^2 \rho \, dx$$

- Aside: dynamics also admit interpretation as a gradient flow for the reversed $\chi^2\text{-}\mathrm{divergence}$

Theorem (ML, Weare, Zhang)

Under suitable technical conditions, $\chi^2(\pi \parallel \rho_t)$ is monotone decreasing. Moreover, there exists C independent of t such that

$$\chi^{2}(\pi \,\|\, \rho_{t}) \leq C e^{-t/\gamma_{\infty}},$$

where $\gamma_{\infty} := \frac{1}{2} \|\pi/\mathcal{Q}\pi\|_{\infty}$.

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- Asymptotic rate of convergence for the **non-interacting ensemble** is controlled by the spectral gap of $\mathcal Q$
- Asymptotic rate of convergence for our scheme is *not* limited by the spectral gap
 - $\bullet\,$ For a narrow proposal, rate $\approx\,2$ independent of proposal

• Consider the double-well potential

$$U(x) = \beta(x^4 - x^2),$$

where β is an inverse temperature parameter controlling the depth of the two wells

• Use Gaussian proposal $q(y \,|\, x) \propto e^{-rac{1}{2\sigma^2}(y-x)^2}$



Figure: Graph of $\pi(x)$ for $\beta = 5$.



Figure: ρ_t according to the mean-field dynamics with $\beta = 5$, $\sigma = 0.0125$ at times t = 0, 2.5, 5, 7.5, 10, 12.5, 15, 17.5, 20, 22.5, ordered left-to-right, then bottom-to-top.



Figure: ρ_t according to the mean-field dynamics for a **non-interacting** ensemble with $\beta = 5$, $\sigma = 0.0125$ at several different times. Note that even by time t = 1000, the dynamics are far from convergence.



Figure: Convergence of $\mathbb{P}_{X \sim \rho}(X \geq 0)$ for interacting dynamics (left) and non-interacting dynamics (right), for several different values of β, σ . Note the different horizontal and vertical axis scales at left and right.

Bayesian hyperparameter estimation

- We consider a multimodal Bayesian posterior sampling problem introduced in [Yao, Vehtari, and Gelman (2020)]
- Goal is to estimate hyperparameters in Gaussian process regression
- Observe data (x_i, y_i) and assume that

$$y_i = f(x_i) + \varepsilon_i,$$

where $f \sim \mathcal{GP}(0, \Sigma)$, $\varepsilon_i \sim \mathcal{N}(0, \sigma^2)$ i.i.d. noise, and

$$\Sigma(x_1, x_2) = \alpha^2 \left(-\frac{(x_1 - x_2)^2}{\rho^2} \right)$$

Place indepedent Cauchy priors on our hyperparameters θ = (α, ρ, σ)
Sample from posterior distribution p(θ | y)

Bayesian hyperparameter estimation



Figure: Posterior (α, ρ) marginal (left) and ρ marginal (right).

Bayesian hyperparameter estimation

Ν	1	10	50
IAT	2111	867	97

Table: Integrated autocorrelation time. We see an **over 20-fold efficiency gain** by considering an interacting scheme with N = 50 instead of a single walker, assuming cost is dominated by the the **number of density evaluations** (usually the bottleneck).

Results not shown

- Similar results for the case of multivariate Gaussian process, where the data $x_i \in \mathbb{R}^3$ (9-dimensional hyperparamter)
 - 16-fold efficiency gain of N = 100 over N = 1
- Paper also considers extension for interaction of a subset of variables
- Ongoing work:
 - Push the advantage to larger ensemble scales ($N \sim 10^5 10^6$) with a modified scheme allowing fast kernel operations for walker interaction and parallel density evaluations
 - Nonlocal proposals can still provide huge computational speedup *even for unimodal densities!*



Figure: IAT as a function of ensemble size for GPR hyperparameter posterior sampling.

- Related work arises by starting with a Fokker-Planck equation for a birth-death stochastic process, then considering a discrete-time particle approximation
 - Y. Lu, J. Lu, and J. Nolen [arXiv:1905.09863]
 - G. Rostkoff, S. Jelassi, J. Bruna, and E. Vanden-Eijnden [arXiv:1902.01843]
 - M. Gabrie, G. Rostkoff, and E. Vanden-Eijnden [arXiv:2105.12603]



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Past Entropically Regularized SDP

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Past Entropically Regularized SDP

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- Semidefinite programs arise in many settings, often from the relaxation of an underlying difficult problem
- The most fundamental examples are from 0-1 **combinatorial optimization**, starting from [Goemans and Williamson (1995)]
 - See also the Lassere Hierarchy, starting with [Lasserre (2001)], as well as [Wainright and Jordan (2008)], for systematic approaches
- My interest in SDP comes from *marginal relaxations* for scientific computing problems:
 - Density functional theory [Khoo, Lin, ML, and Ying (2020)]
 - Continuous global optimization [Chen, Khoo, and ML (2020)]
 - Quantum many-body problems [Lin and ML (2022)], [Khoo and ML (2022)]

Max-Cut problem

• Given a graph (V, E), want to color the vertices white/black so that as many edges as possible connect unlike colors



Figure: Maximum cut of a small graph

• Formally, if the vertices are indexed by i = 1, ..., n, want to solve:

$$\min_{\{-1,1\}^n}\sum_{i,j:(i,j)\in E}x_ix_j$$

• NP-complete!

• Hard to do much better than enumerating all 2^n possibilities for $x = (x_i)$

Goemans-Williamson relaxation

• On the domain $x \in \{-1, 1\}^N$, rewrite the objective:

$$\sum_{i,j:(i,j)\in E} x_i x_j = \sum_{i,j=1}^N A_{ij} x_i x_j = x^\top A x = \operatorname{Tr}[A x x^\top],$$

where A is the adjacency matrix of the graph

Let

$$X = xx^{\top}$$

and observe that $diag(X) = 1, X \succeq 0$

If we optimize X ∈ ℝ^{n×n} subject only to these constraints, we obtain a *relaxation* of the original problem, providing a *lower bound* on the optimal value

Goemans-Williamson relaxation

Specifically

 $\begin{array}{ll} \underset{X \in \mathbb{R}^{n \times n}}{\text{minimize}} & \operatorname{Tr}[AX] \\ \text{subject to} & X \succeq 0, \\ & \operatorname{diag}(X) = 1 \end{array}$

- This relaxation is due to Goemans and Williamson (1995)
 - They also provide a randomized rounding procedure from the solution X to an element x ∈ {−1,1}ⁿ
 - Plugging in x yields an upper bound guaranteed to yield an upper bound achieving an **approximation ratio** of

$lpha pprox {\sf 0.878}$

- In fact it is conjectured [Khot et al (2007)] to be the best possible guaranteed approximation ratio, and it is known [Trevisan et al (2000)] that \geq 0.941 is NP-hard
- Aside from interest in Max-Cut per se, the GW relaxation is the **prototypical** semidefinite relaxation and SDP

• A general SDP can be written

$$\begin{array}{ll} \underset{X \in \mathbb{R}^{n \times n}}{\text{minimize}} & \operatorname{Tr}[CX]\\ \text{subject to} & X \succeq 0,\\ & \operatorname{Tr}[A_k X] = b_k, \ k = 1, \dots, m, \end{array}$$

though sometimes alternative equivalent presentations may be preferred based on structure

Review of optimization approaches

- How to solve an SDP? There are several categories of methods:
 - Interior point methods: strong convergence guarantees but very poor scaling per iteration
 - Augmented Lagrangian / ADMM-type methods: weaker convergence guarantees but optimal-in-general O(n³) scaling per iteration (e.g., SDPNAL, cf. Toh et al)
 - Low-rank methods: exploit low-rank assumption on solution, e.g., SDPLR [Burer and Monteiro (2003)] and SketchyCGAL [Yurtsever et al (2021)]
 - TCS-style algorithms: e.g., MMWU [Arora and Kale (2007)]
- We want linear scaling (assuming sparsity of the cost and constraint matrices) *without* a low-rank assumption
 - The MMWU has nice theoretical scaling guarantees but impractical to implement!
- **This work:** first practical linear-scaling algorithm achieving a fixed approximation ratio for Max-Cut (though applies more broadly)

- Inspired by the success of the **entropic regularization of optimal transport** [Cuturi 2013], which is a *linear program*, we are motivated to consider the entropic regularization of *SDP* as a general computational tool
 - In addition to quantum statistical mechanics literature, see [Krechetov (2019)], [Lin and ML (2022)], and [Pavlov et al (2022)] for other uses
- For a positive definite matrix X define the von Neumann entropy

$$S(X) = \operatorname{Tr}[X \log X] - \operatorname{Tr}[X]$$

• Can be viewed as a quantum analog of Shannon's classical entropy, fundamental in quantum information theory, cf. [Nielsen and Chuang]

- Von Neumann entropy noncommutative/quantum analog of classical entropy, appearing in quantum information theory
- Consider the regularized problem, where $\beta \in (0, \infty)$ is a regularization parameter (*'inverse temperature'*):

$$\begin{array}{ll} \underset{X \succ 0}{\text{minimize}} & \operatorname{Tr}[CX] + \beta^{-1}S(X) \\ \text{subject to} & \operatorname{Tr}[A_kX] = b_k, \quad k = 1, \dots, m \end{array}$$

Note that the entropy acts as a *barrier* to the boundary of {X ≥ 0} and also makes the problem *strictly convex*

Dual problem

- Restrict to case of diagonal constraint diag(X) = b for simplicity
- The dual problem is unconstrained:

$$\max_{\lambda \in \mathbb{R}^n} \quad b \cdot \lambda - \beta^{-1} \mathsf{Tr} \left[e^{-\beta(\mathcal{C} - \operatorname{diag}(\lambda))} \right]$$

- In quantum statistical mechanics interpretation:
 - $\mathcal{C}_{\lambda} := \mathcal{C} \operatorname{diag}(\lambda)$ is an effective Hamiltonian
 - β is the inverse temperature
 - $Z_{\beta,\lambda} := \operatorname{Tr}[e^{-\beta C_{\lambda}}]$ is the partition function
 - X_{β,λ} := e^{−βC_λ} is the (unnormalized) density operator
 - $F_{\beta,\lambda} := -\beta^{-1} Z_{\beta,\lambda}$ is (kind of) the free energy
- The gradient of the dual objective

$$b - \operatorname{diag}(X_{\beta,\lambda})$$

• Hence we want to find a **dual solution** λ^* such that $\operatorname{diag}(X_{\beta,\lambda^*}) = b$, and this X_{β,λ^*} is in fact the **primal solution** of the regularized problem

Stochastic diagonal estimation

- How to compute $\operatorname{diag}(X_{\beta,\lambda}) = \operatorname{diag}(e^{-\beta C_{\lambda}})$?
 - Forming the matrix exponential, even if C_{λ} is sparse, consumes $O(n^3)$ cost
- Randomized approach which has appeared in the GPR literature [Mathur et al (2021)]:

$$\operatorname{diag}(X) = \mathbb{E}_{z \sim \mathcal{N}}\left[(X^{1/2}z) \odot (X^{1/2}z) \right],$$

where z is a standard Gaussian random vector

- We prove concentration bounds for the corresponding estimator
 - Relative error of estimator is essentially problem-independent
- Hence we only need to compute matrix-vector multiplications

$$X_{\beta,\lambda}^{1/2}z = e^{-\frac{\beta}{2}C_{\lambda}}z$$

• Fast matrix-free algorithm available [Al-Mohy and Higham (2011)], or alternatively matrix-free Chebyshev expansion [Driscoll, Hale, and Trefethen (2014)]

- In fact for Max-Cut we do not apply dual gradient ascent, but introduce a specialized **noncommutative matrix scaling** approach
 - But still makes use of the same estimator
- Not discussed: 'fermionic' entropic regularization allows us to solve other problems, such as the spectral embedding of a graph with n vertices into ℝ^k
 - Improve $O(nk^2)$ of standard eigensolver approach to O(nk) randomized approximate algorithm

Max-Cut results: convergence profile



Figure: Convergence profile for various system sizes *n* and regularization parameters β (solid lines for $\beta = 10$, dotted lines for $\beta = 32$, dashed lines for $\beta = 100$)

Max-Cut results: approximation ratio



Figure: Approximation ratio obtained as a function of system size, for various regularization parameters β

MCMC:

 ML, J. Weare, and A. Zhang, Ensemble Markov chain Monte Carlo with teleporting walkers, submitted (anticipated SIAM/ASA Journal on Uncertainty Quantification)

SDP:

• ML, Fast randomized entropically regularized semidefinite programming, preprint [arXiv:2303.12133]

Thank you very much for your attention!